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B.E. / B.Tech. (Full Time) DEGREE END SEMESTER EXAMINATIONS, NOV/ DEC 2011
ELECTRICAL AND ELECTRONICS ENGINEERING BRANCH
THIRD SEMESTER – (REGULATIONS 2008)

EE 9201 – CONTROL SYSTEMS

Time : 3 hrs

Max . Mark: 100

Answer All Questions

Part – A (10 x 2 = 20 Mark)

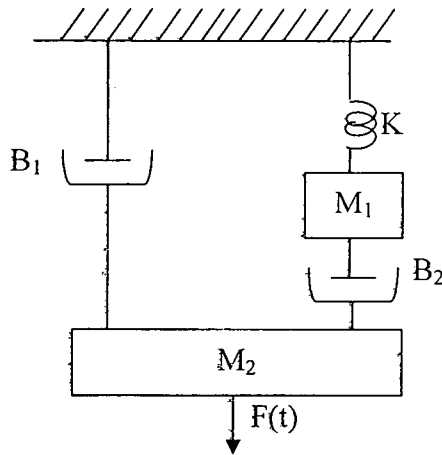
- 1) Distinguish between time varying and time invariant systems.
- 2) Write the force current analogy of mechanical rotational and translational systems.
- 3) Define peak time and rise time.
- 4) List the advantages of the Root locus.
- 5) Write the correlation between time and frequency response.
- 6) Define phase and gain cross over frequency.
- 7) State Nyquist stability criterion.
- 8) What do you understand by BIBO stability and asymptotic stability?
- 9) What is meant by state and state variables?
- 10) Obtain the transfer function of the system defined by the following state equations.

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u$$

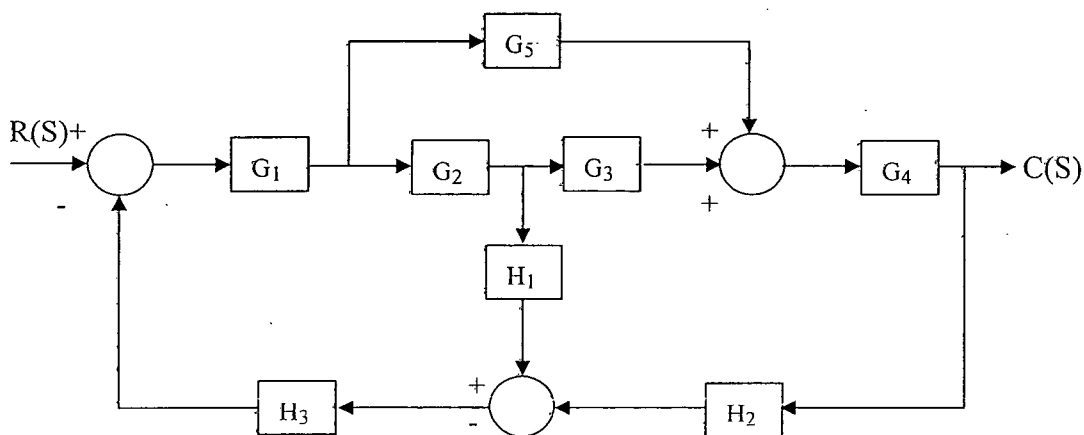
$$y = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

PART – B (5X16= 80 Marks)

11. i. Draw force- voltage analogous circuit for the mechanical system shown below and write the equation.



ii. Using block diagram reduction technique find the transfer function given below.



(8+8)

12.a)(i) Find \$k_p, k_v, k_a\$ for the following system. Find \$e_{ss}\$ for \$r(t) = 1 + t\$

(6)

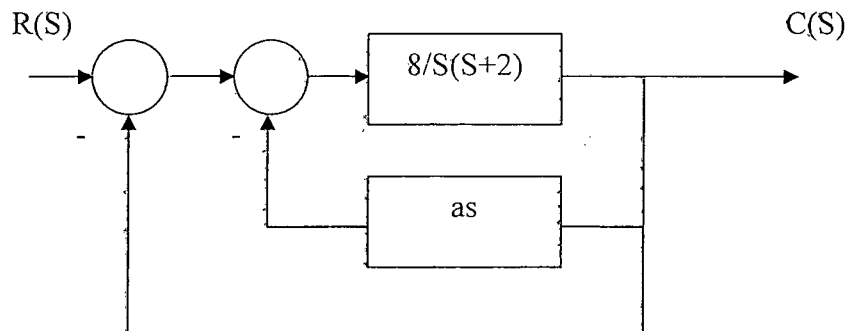
$$G(s) = 100 / s^2(s+2)(s+5)$$

(ii) A system is as shown below. In absence of derivative feedback (\$a=0\$) find \$\delta\$ and \$\omega_n\$.

(iii) Find 'a' to increase \$\delta\$ to 0.7.

(iv) Find \$M_p\$ in (ii) and (iii)

(3+3+4)



(Or)

- b). Sketch the root locus for the unity feedback system whose open loop transfer function is given by

$$G(s)H(s) = \frac{(s+4)}{s(s^2+6s+13)} \quad (16)$$

- 13.a) Draw the Bode diagram for the following transfer function.

$$G(s) = \frac{(1+0.2s)(1+0.025s)}{s^3(1+0.001s)(1+0.005s)} \quad (16)$$

(Or)

- b) Sketch the Polar plot for the transfer function and determine the gain margin and phase margin.

$$G(s) = \frac{(s+6)}{s^2(1+2s)(1+8s)} \quad (16)$$

- 14.a.i. The open loop transfer function of a closed loop system with unity feedback is

$$G(s) = K / (s+2)(s+4)(s^2+6s+25). \text{ Using Routh criterion, determine the stability of the system.} \quad (6)$$

- ii. Using Routh criterion, determine the stability of the system represented by the following characteristic equation. $s^6 + 3s^5 + 5s^4 + 9s^3 + 8s^2 + 6s + 4 = 0$. (6)

- iii. What is an auxiliary polynomial? What is its order? What information does the auxiliary polynomial give? (4)

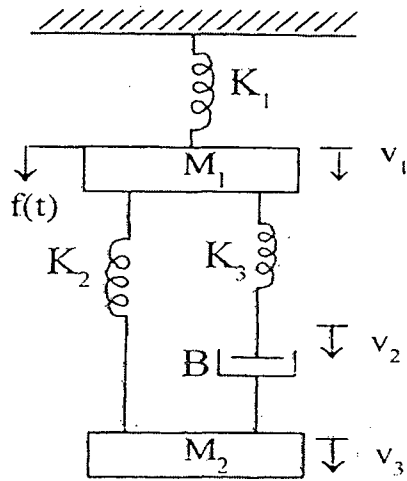
(Or)

- b). Sketch the Bode plot of the given transfer function

$$G(s) = \frac{48(s+10)}{s(s+20)(s^2+24s+16)}$$

Comment on the stability of the system. (16)

15. a. i Obtain the state model of the system shown in fig.



(8)

ii. A system has the governing equation $d^3y/dt^3 + 5 dy/dt + 4y = u(t)$. Find the state model of the system. (8)

(Or)

b. i. State controllability and observability theorem. (4)

(4)

ii. Check the controllability and observability of the system.

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 0 \\ 1 & -4 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad C = [1 \quad 1 \quad 0]$$

(8)
